

Basic Computations in Multivariable Calculus Made Easy

I. Vector Geometry

Single Variable Functions

For single variable functions we use the notation $f[x_]:=$.

```
f[x_] := x ^ 2  
f[2]  
4
```

Multi-Variable Functions

For functions of two or more variables we just use a comma in between each variable and make sure to use the underscore i.e for two variables it becomes $f[x_,y_]:=$ and for three it becomes $f[x_,y_,z_]:=$ and so forth.

```
f[x_, y_] := x ^ 2 + y ^ 2  
f[1, 2]  
5
```

```
g[x_, y_, z_] := 2 x + y + z
g[1, 1, 1]
4
```

Dot Product

The notation for dot product is given by $\{a,b,c\}$ [dot] $\{x,y,z\}$ or $\{a,b,c\}.\{x,y,z\}$ i.e just put a period in between the arrays.

```
{1, 0, 0} . {0, 1, 0}
0
{1, 2, 3} . {1, 1, 1}
6
```

Orthogonal Projection

The notation for computing the orthogonal projection is given by `Projection[u,v]`.

```
u := {0, 1}
v := {1, 0}
Projection[u, v]
{0, 0}
```

Cross Product

The notation for the cross product is given by `Cross[u,v]` where u,v are vectors entered in like above i.e $u=\{a,b,c\}$ and $v=\{x,y,z\}$.

```
Cross[{1, 0, 0}, {0, 1, 0}]
{0, 0, 1}
```

II. Vector Calculus

Length (Norm) of Vectors

To compute the length or norm of a vector we use `Norm[{x,y,z}]`.

```
a := {1, 1}
Norm[a]
 $\sqrt{2}$ 
```

Differentiating Vector-Valued Functions

To differentiate a vector valued function, we think of it as a $n \times 1$ matrix (or similarly $1 \times n$) and use `D[{x_1,...,x_n},{t}]`.

```
D[{2 t, t}, {t}]
{2, 1}

a := {2 t, t}
D[a, {t}]
{2, 1}

f[t_] := {t, t}
f'[t_]
{1, 1}
```

Integrating Vector-Valued Functions

To integrate a vector valued function we use `Integrate[{x_1,...,x_n},{t,0,t}]`.

```

a = {2 t, t}
Integrate[a, {t, 0, t}]
{2 t, t}
{t2,  $\frac{t^2}{2}$ }

```

Arc-Length Function

We've already talked about how to define functions and now with the above we know how to integrate them. It follows that $s[t_]:=Integrate[Norm[D[{x_1,...,x_n},{t}],{t,0,t}]$ is one way to compute the arc-length function.

```

s[t_] := Integrate[Norm[D[{t, t}, {t}], {t, 0, t}]
s[t]
 $\sqrt{2} t$ 

```

Curvature for Plane and Space Curves

Again, we will just be combining previous definitions and so it follows that one way to denote the curvature is $k[t_]:=Norm[Cross[r'[t], r''[t]]/Norm[r'[t]]^3$. Below we compute the curvature of a line, which should be zero.

```

r[t_] := {t, 0, 0}
k[t_] := Norm[Cross[r'[t], r''[t]]/Norm[r'[t]]^3
k[t]
0

```

Unit Tangent and Normal Vectors

Arguably two of the most annoying things to compute in multivariable calculus is now simplified! We just use the command `Normalize[v]`. Below is an example with the standard helix and lastly we show that T, N are perpendicular for all t . There are letters which are previously defined in Mathematica and for that reason $g(t) = T(t)$ and $h(t) = N(t)$. The notation is given by $g(t) = \text{Normalize}[r'[t]]$ and $N(t) = \text{Normalize}[g'[t]]$.

```
r[t_] := {Cos[t], Sin[t], t}
```

```
Normalize[r'[t]]
```

$$\left\{ -\frac{\sin[t]}{\sqrt{1 + \text{Abs}[\cos[t]]^2 + \text{Abs}[\sin[t]]^2}}, \frac{\cos[t]}{\sqrt{1 + \text{Abs}[\cos[t]]^2 + \text{Abs}[\sin[t]]^2}}, \frac{1}{\sqrt{1 + \text{Abs}[\cos[t]]^2 + \text{Abs}[\sin[t]]^2}} \right\}$$

```
g[t_] := {-Sin[t]/Sqrt[2], Cos[t]/Sqrt[2], 1/Sqrt[2]}
```

```
Normalize[g'[t]]
```

$$\left\{ -\frac{\cos[t]}{\sqrt{2} \sqrt{\frac{1}{2} \text{Abs}[\cos[t]]^2 + \frac{1}{2} \text{Abs}[\sin[t]]^2}}, -\frac{\sin[t]}{\sqrt{2} \sqrt{\frac{1}{2} \text{Abs}[\cos[t]]^2 + \frac{1}{2} \text{Abs}[\sin[t]]^2}}, 0 \right\}$$

```
h[t_] := {-Cos[t], -Sin[t], 0}
```

```
Dot[h[t], g[t]]
```

```
0
```

III. Differentiation in Several Variables

Partial Derivatives

Given a function $f(x_1, \dots, x_n)$ the command $D[f, x_j]$ gives the partial with respect to the variable x_j . The commands $D[f, \{x_j, n\}]$, $D[f, x_1, x_2, \dots]$ give the x_j derivative n -times and mixed partial derivative respectively. You can also play with the $D[f, \{x_1, n\}, \{x_2, m\}, \dots]$. This will give the x_j derivative computed n -times first, then the x_2 derivative computes m -times and so forth.

```
f[x_, y_] := x^2 + y^2
```

```
D[f[x, y], x]
```

```
2 x
```

```
D[f[x, y], {x, 3}]
```

```
2 x
```

```
0
```

```
g := Cos[x + y]
```

```
D[g, x]
```

```
-Sin[x + y]
```

Gradient (and general derivative)

Given a real-valued function $f = f(x_1, \dots, x_n)$, the command $D[f, \{x_1, \dots, x_n\}]$ gives its derivative (or gradient). The command $D[\{f^1, \dots, f^m\}, \{x_1, \dots, x_n\}]$ gives the Jacobian i.e derivative of f , an $m \times n$ matrix.

```
f := x^2 + y^2
```

```
D[f, {{x, y}}]
```

```
{2 x, 2 y}
```

```
g := {x, y}
```

```
D[g, {{x, y}}]
```

```
{2 x, 2 y}
```

```
{{1, 0}, {0, 1}}
```

Hessian Matrix (second derivative test)

The Hessian matrix of a real valued function f is given by the command `D[f,{{x_1,...,x_n},2}]`. To check that the example below makes sense, just remember that the Hessian is computed by taking the gradient of the gradient (transpose).

```
f := x^2 + y^2  
D[f, {{x, y}, 2}]  
{{2, 0}, {0, 2}}
```

IV. Integration with Multiple Variables

Single Variable Integration

To integrate a real-valued single variable function $f(x)$, use the command `Integrate[f,x]` to return the indefinite integral and `Integrate[f,{x,a,b}]` to return the definite integral.

```
f := x
Integrate[f, {x, 0, 1}]

$$\frac{1}{2}$$

```

Several Variable Integration

To integrate a real-valued function $f=f(x_1,\dots,x_n)$ we use also have two commands. The first is `Integrate[f,{x_1,-,-},{x_2,-,-},...,{x_n,-,-}]`. The dashes after the variable x_j are its lower and upper bounds respectively. The second command is `Integrate[f,{x_1,...,x_n} \in reg]`. The term `reg` refers to region in which Mathematica has a few previously defined such as the sphere, disk, circle, etc.

```
f := 1
Integrate[f, {x, y} \in Disk[]]

$$\pi$$

g := 2 - x - y
Integrate[g, {x, 0, 2}, {y, 0, 2 - x}]

$$\frac{4}{3}$$

```


V. Fundamental Theorems of Vector Analysis

Divergence

Given a vectors-valued function $f=(f^1,\dots,f^n)$, its divergence is given by the command `Div[{f^1,...,f^n}, {x_1,...,x_n}]`. Moreover, one can use `Div[{f^1,...,f^n},{x_1,...,x_n}, chart]` to give the divergence in specific coordinate variables. We won't illustrate this example since it is a bit fancy. A short cut is to use "esc +

del+esc, ctrl +“ which produces $\nabla_{\{x,y,z\}}$.

```
f := {x, y, z}
∇{x,y,z} · {y, -x, z}
1
```

Curl

Given a vectors-valued function $f=(f^1,\dots,f^n)$, its divergence is given by the command `Curl[f,{x_1,...,x_m}]`. Additionally we can compute the curl in a specific coordinate chart by using `Curl[f,{x_1,...,x_m}, chart]`.

```
Curl[{x * y, Exp[x], y + z}, {x, y, z}]
{1, 0, ex - x}
```