4 Solving first order linear ODE. Newton’s law of cooling

Linear equations and systems will take a significant part of the course. Here we start with the simplest linear problem:

**Definition 1.** The first order ODE of the form

\[ y' + p(x)y = q(x) \]  \hspace{1cm} (1)

is called linear.

Here \( p(x) \) and \( q(x) \) are given functions of the independent variable \( x \). Equation (1) is called **homogeneous** if \( q(x) \equiv 0 \), and **non-homogeneous** in the opposite case. There are several methods of solving (1) (of finding the general solution to (1)). We will consider the method of integrating factor and the variation of the constant method.

4.1 The method of integrating factor

First, recall from Calculus that for any two differentiable functions \((u(x)v(x))' = u'(x)v(x) + u(x)v'(x)\). Using the last formula, we can try to find such a function \( \mu(x) \), which is called an integrating factor, that turns the left-hand side of the equation (1) into the derivative of the product of two functions:

\[ \mu(x)y' + \mu(x)p(x)y = \mu(x)q(x), \]

which means that one should have

\[ u(x) = \mu(x), \quad u'(x) = \mu(x)p(x), \]

from where we get that

\[ u'(x) = u(x)p(x) \Rightarrow u(x) = e^{\int p(x) \, dx}. \]

In the last expression we can take any antiderivative for \( p(x) \) because we are interested in an integrating factor (in words, you do not need to worry about the arbitrary constant). Finally, returning to the original variables, we find that an integrating factor for (1) can be found as

\[ \mu(x) = e^{\int p(x) \, dx}. \]

Therefore, to solve the linear ODE (1), you need to find an integrating factor \( \mu(x) \). According to the reasoning above, after the multiplication of the both sides of the equation by \( \mu(x) \), it follows that

\[ (\mu(x)y(x))' = \mu(x)q(x), \]

Hence,

\[ \mu(x)y(x) = \int \mu(x)q(x) \, dx \Rightarrow y(x) = \frac{1}{\mu(x)} \int \mu(x)q(x) \, dx, \]

which gives the general solution to (1).

Here are a few examples.
Example 2.

\[ y' - y = 4e^x. \]

This is obviously a linear equation with \( p(x) = -1 \) (note the minus sign!) and \( q(x) = 4e^x \). The integrating factor is (using the notation \( \exp(x) := e^x \) for the exponential function)

\[ \mu(x) = \exp(\int (-1) \, dx) = \exp(-x) = e^{-x}. \]

Hence,

\[ e^{-x}y = \int 4e^{-x}e^x \, dx = 4x + C. \]

The final answer is

\[ y(x) = 4xe^x + Ce^x. \]

Example 3.

\[ (2x + 1)y' = 4x + 2y. \]

First, we rewrite this equation as

\[ y' - \frac{2}{2x + 1}y = \frac{4x}{2x + 1}, \]

assuming that \( 2x + 1 \neq 0 \). Here, obviously, \( p(x) = -\frac{2}{2x+1} \) and \( q(x) = \frac{4x}{2x+1} \). An integrating factor can be found as

\[ \mu(x) = \exp(-\int \frac{2}{2x+1} \, dx) = \exp(-\ln |2x + 1|) = \frac{1}{|2x + 1|}, \]

and since we assume that \( 2x + 1 \neq 0 \) and our integrating factor can be always multiplied by \(-1\), we can drop the absolute value here. Finally,

\[ \mu(x) = \frac{1}{2x + 1}. \]

This implies that

\[ \left( \frac{y}{2x + 1} \right)' = \frac{4x}{(2x + 1)^2} \implies \frac{y}{2x + 1} = \int \frac{4x \, dx}{(2x + 1)^2} = \int 2(2x + 1) - 2 \frac{1}{(2x + 1)^2} \, dx = \ln |2x + 1| + \frac{1}{2x + 1} + C. \]

Finally,

\[ y(x) = (2x + 1)(C + \ln |2x + 1|) + 1, \]

which is the general solution to our equation.

Example 4.

\[ (x + y^2)y' = y. \]

First look tells us that this equation is not linear. And this is indeed true if we say, that this equation is not linear with respect to the dependent variable \( y(x) \). However, sometimes it is useful to perform the following trick: Exchange the role of the variables \( x \) and \( y \) in the equation. To accomplish this formally, we can use the Leibnitz notation:

\[ (x + y^2) \frac{dy}{dx} = y \implies x + y^2 = y \frac{dx}{dy}, \]

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hence

\[ x'(y) - \frac{1}{y}x = y, \]

which is a linear ODE with respect to the unknown function \( x(y) \). We also have \( p(y) = -\frac{1}{y} \) and \( q(y) = y \).

You may recall that in Lecture 2 I already stated that it is not correct to treat \( \frac{dy}{dx} \) as a fraction, however, as in the case of separable equations, we will not get a wrong answer by performing the steps outlined above. A rigorous justification of the considered approach would rely on the implicit function theorem from your Calculus course.

The integrating factor here is

\[ \mu(y) = \frac{1}{y}, \]

and the general solution is (fill in the omitted steps)

\[ x(y) = y^2 + Cy. \]

4.2 The variation of the constant method

There is another method that also works in more general situations. Therefore, I will briefly describe it here.

The first step in this method is to solve the homogeneous linear equation

\[ y' = -p(x)y, \]

which is a separable equation. The general solution is given by

\[ y(x) = Ce^{-\int p(x)\,dx}. \]

Now the crucial step is to assume that the arbitrary constant in the solution above is not a constant but an unknown function depending on \( x \):

\[ y(x) = C(x)e^{-\int p(x)\,dx}, \]

and plug this expression into the original non-homogeneous equation \( y' + p(x)y = q(x) \):

\[
\left(C(x)e^{-\int p(x)\,dx}\right)' + p(x)C(x)e^{-\int p(x)\,dx} = q(x) \implies \]
\[
C'(x)e^{-\int p(x)\,dx} - p(x)C(x)e^{-\int p(x)\,dx} + p(x)C(x)e^{-\int p(x)\,dx} = q(x). \]

Note that two terms cancel, this should be always true for this method: Something must be canceled. Now we obtain,

\[ C'(x)e^{-\int p(x)\,dx} = q(x) \implies C'(x) = q(x)e^{\int p(x)\,dx} \implies C(x) = \int q(x)e^{\int p(x)\,dx}\,dx + C_1. \]

Finally, putting everything together:

\[ y(x) = \left(\int q(x)e^{\int p(x)\,dx}\,dx + C_1\right)e^{-\int p(x)\,dx}, \]
and this gives the general solution to the linear ODE (1).

Consider again the equation
\[ y' - y = 4e^x. \]

Using the variation of the constant method, we first solve
\[ y' - y = 0 \implies y(x) = Ce^x. \]

Now assume that \( C = C(x) \) and plug \( C(x)e^x \) into the original non-homogeneous equation
\[ C'(x)e^x + C(x)e^x - C(x)e^x = 4e^x \implies C'(x) = 4 \implies C(x) = 4x + C_1. \]

Hence we get the solution
\[ y(x) = C(x)e^x = 4xe^x + C_1e^x, \]
which, as expected, coincides with the solution found earlier by the method of the integrating factor. You should practice this method on the rest of the examples in this lecture.

4.3 Newton’s law of cooling

To illustrate applications of the technique I have just described, consider a system when an object of the initial temperature \( T_0 \) is placed in the surrounding media which has prescribed temperature \( T_{out}(t) \), where \( t \) denotes time, thus we allow that \( T_{out}(t) \) can change with time, however, we have full information about this temperature, i.e., we know \( T_{out}(t) \). For a more concrete example think about a cup of tea, which is put inside a refrigerator. Common sense tells us that sooner or later the temperature of the object should approach the temperature of the surrounding media, but how long does it usually take? To answer this question, we recall Newton’s law of cooling that states that

the rate of change of the temperature of an object is proportional to the difference between its own temperature and the ambient temperature (i.e. the temperature of its surroundings).

Since the instantaneous rate of change mathematically is given by the derivative, we end up with the IVP
\[ \dot{T} = -k(T - T_{out}(t)), \quad T(0) = T_0. \]

Here, again, \( T(t) \) is the temperature of the object that we would like to determine (unknown function), \( T_0 \) is the initial temperature of the object, \( T_{out}(t) \) is the prescribed ambient temperature, which we know, \( k \) is the constant of proportionality that characterize the ability of the object to exchange the heat energy, and which depends on the material. The sign minus is taken so that, if \( k > 0 \), our object would decrease its temperature if \( T_{out} < T_0 \) and increase if \( T_{out} > T_0 \).

Note that if we had \( T_{out} \) constant, then the resulting ODE would be separable.

I rewrite the equation in the standard form
\[ \dot{T} + kT = kT_{out}(t). \]

First solve the homogeneous equation \( \dot{T} + kT = 0 \), which has the solution \( T(t) = Ce^{-kt} \). Now assume that \( C = C(t) \) (I am using the variation of the constant method),
\[ C'(t)e^{-kt} = kT_{out}(t) \implies C(t) = \int kT_{out}(t)e^{kt} \, dt. \]
The general solution is

\[ T(t) = e^{-kt} \int kT_{\text{out}}(t)e^{kt} \, dt, \]

where the integral includes the arbitrary constant \( C_1 \), which has to be determined from the initial condition.

As an important particular case consider \( T_{\text{out}}(t) = \text{constant} = T_{\text{out}} \). In this case the formula for the general solutions simplifies to (check this)

\[ T(t) = T_{\text{out}} + (T_0 - T_{\text{out}})e^{-kt}, \]

which shows, as expected, that

\[ \lim_{t \to \infty} T(t) = T_{\text{out}}. \]

### 4.4 First glimpse of an electric circuit

Linear ODE find a lot of applications when dealing with electric circuits. Here is our first example.

It is well known (an experimental fact), that in a circuit with resistance \( R \) (measured in ohms) and inductance \( L \) (in henrys) the dependence of the voltage \( E(t) \) (in volts) and the current \( I(t) \) (in amps) is given by

\[ E(t) = RI + L \frac{dI}{dt}, \]

which is a first order linear equation. In general of course \( E(t) \) is a function of time. Consider an example when \( E = E_0 = \text{const} \) and \( I(0) = I_0 \).

The solution (you should fill in the details) is

\[ I(t) = \frac{E_0}{R} + \left( I_0 - \frac{E_0}{R} \right) e^{-(R/L)t}. \]

We can see from this solution that when \( t \to \infty \) the current approaches the steady state \( E_0/R \). It is a good exercise to find the current in the case when \( E(t) = E_0 \sin 2\pi nt \) for some constant \( n \in \mathbb{N} \).

Another equation is obtained for a circuit with a capacitor, with capacitance \( C \) (in farads), resistance \( R \) and voltage \( E(t) \). In this case the empirical law says that

\[ R \frac{dQ}{dt} = E(t) - \frac{Q}{C}, \]

where \( Q(t) \) is the charge on the capacitor measured in coulombs. Note for future lectures that there is a connection between the current and the charge

\[ I = \frac{dQ}{dt}. \]

### 4.5 Problems for a mathematically inclined student

1. Show that the linear equation (1) stays linear for any change of the independent variable \( x = \phi(t), \, \phi \in C^{(1)}. \)

2. Assume that we are given the family of the integral curves of (1). Fix point \( x \) and consider tangent lines to different integral curves at \( x \). Show that they all cross at the same point \( S \) and find its coordinates.